

Totally conservative integration method for N -body problem and its equilibrium solutions

Yukitaka Minesaki

Tokushima Bunri University

minesaki@tks.bunri-u.ac.jp

Abstract

We design a precise integration method for the general N -body problem (GNBP) which maintains all conserved quantities. Our method prove to retain the same orbits of equilibrium solutions as the original GNBP. This method is based on a kind of 2nd-order symplectic integrators, logarithmic Hamiltonian leapfrog ((LogH)₂), and involves an energy-preserving parameter. Until our method, no integration method was known to hold both preservation of all conserved quantities and the existence of triangular Lagrangian solutions.

Introduction

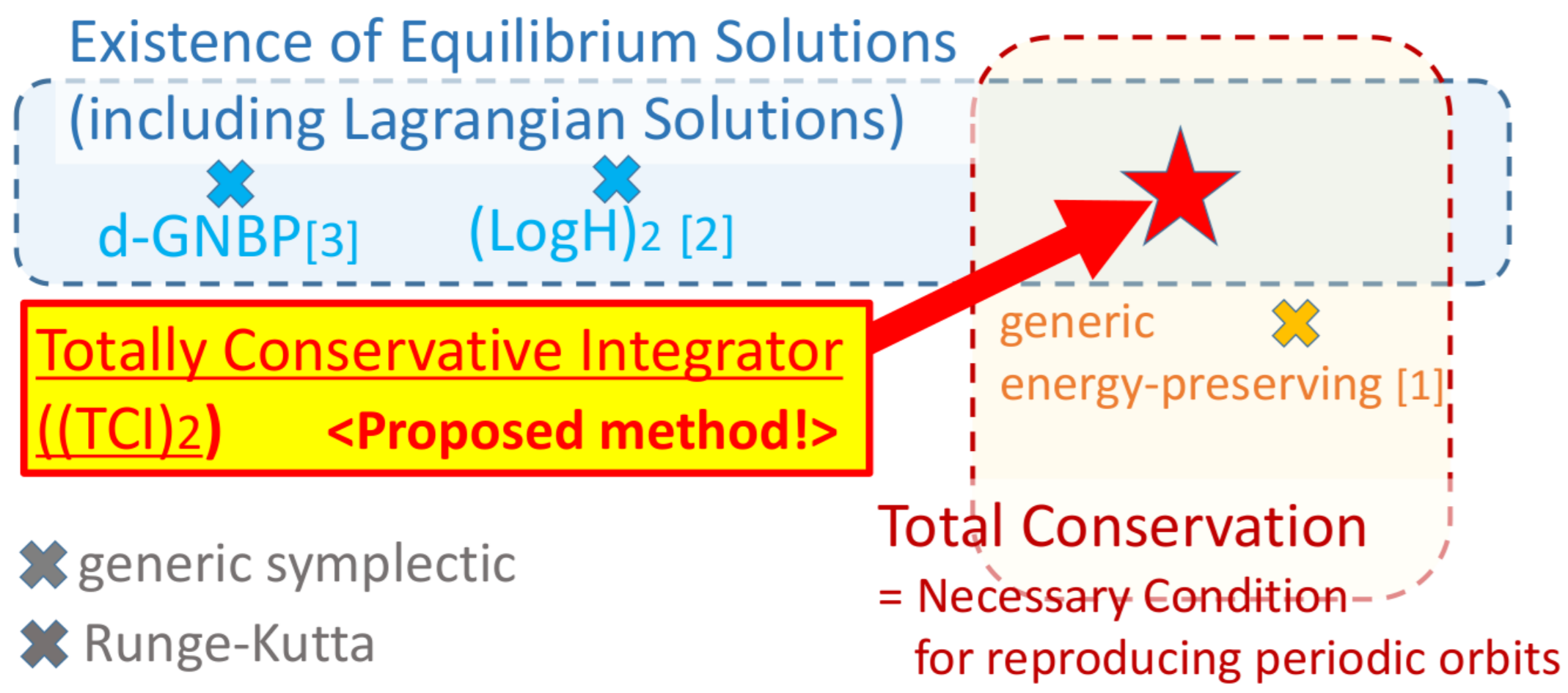


Figure 1: Various integrators for GNBP

Totally conservative integration method for general 3-body problem (G3BP)

For simplicity, we describe only a 2nd-order totally conservative integration method ((TCI)₂) for G3BP in the relative frame:

$$\begin{cases} \mathbf{v}_{12}^{(l+1)} + \mathbf{v}_{23}^{(l+1)} - \mathbf{v}_{13}^{(l+1)} = \mathbf{0}, \\ \mathbf{q}_{ij}^{(l+\frac{1}{2})} = \mathbf{q}_{ij}^{(l)} + \frac{\Delta s}{2} \frac{\mathbf{v}_{ij}^{(l)}}{T_R(\mathbf{v}^{(l)}) - E^{(0)}}, 1 \leq i < j \leq 3, \quad t^{(l+\frac{1}{2})} = t^{(l)} + \frac{\Delta s}{2} \frac{1}{T_R(\mathbf{v}^{(l)}) - E^{(0)}}, \\ \sum_{i=1}^{j-1} m_i \left(\frac{U_R(\mathbf{q}^{(l+\frac{1}{2})})}{\alpha^{(l+\frac{1}{2})} \Delta s} (\mathbf{v}_{ij}^{(l+1)} - \mathbf{v}_{ij}^{(l)}) - \frac{M \mathbf{q}_{ij}^{(l+\frac{1}{2})}}{|\mathbf{q}_{ij}^{(l+\frac{1}{2})}|^3} \right) = \sum_{i=j+1}^3 m_i \left(\frac{U_R(\mathbf{q}^{(l+\frac{1}{2})})}{\alpha^{(l+\frac{1}{2})} \Delta s} (\mathbf{v}_{ji}^{(l+1)} - \mathbf{v}_{ji}^{(l)}) - \frac{M \mathbf{q}_{ji}^{(l+\frac{1}{2})}}{|\mathbf{q}_{ji}^{(l+\frac{1}{2})}|^3} \right), j = 2, 3, \\ \mathbf{q}_{ij}^{(l+1)} = \mathbf{q}_{ij}^{(l+\frac{1}{2})} + \frac{\Delta s}{2} \frac{\mathbf{v}_{ij}^{(l+1)}}{T_R(\mathbf{v}^{(l+1)}) - E^{(0)}}, 1 \leq i < j \leq 3, \quad t^{(l+1)} = t^{(l+\frac{1}{2})} + \frac{\Delta s}{2} \frac{1}{T_R(\mathbf{v}^{(l+1)}) - E^{(0)}}, \end{cases}$$

where Δs : a fictitious time step, the total kinetic energy: $T_R(\mathbf{v}) \equiv \frac{\sum_{i=1}^2 \sum_{j=i+1}^3 m_i m_j |\mathbf{v}_{ij}|^2}{2(m_1 + m_2 + m_3)}$,

the total potential: $U_R(\mathbf{q}) \equiv -\sum_{i=1}^2 \sum_{j=i+1}^3 \frac{m_i m_j}{|\mathbf{q}_{ij}|}$, the total energy: $E^{(0)} \equiv T_R(\mathbf{v}^{(0)}) + U_R(\mathbf{q}^{(0)})$, the

total potential: $M = m_1 + m_2 + m_3$, and energy-preserving parameter: $\alpha^{(l+1/2)}$. In the case of $\alpha^{(l+1/2)} = 1$, (TCI)₂ coincides with (LogH)₂ [2].

$$(\text{LogH})_2 \xrightarrow{\Delta s \rightarrow 0} \text{G3BP in the relative frame: } \begin{cases} \mathbf{v}_{12} + \mathbf{v}_{23} - \mathbf{v}_{13} = \mathbf{0}; \quad \frac{d\mathbf{q}_{i,j}}{dt} = \mathbf{v}_{i,j}, \quad 1 \leq i < j \leq 3; \\ \sum_{i=1}^{j-1} m_i \left(\frac{d\mathbf{v}_{i,j}}{dt} + \frac{M \mathbf{q}_{i,j}}{|\mathbf{q}_{i,j}|^3} \right) = \sum_{i=j+1}^3 m_i \left(\frac{d\mathbf{v}_{j,i}}{dt} + \frac{M \mathbf{q}_{j,i}}{|\mathbf{q}_{j,i}|^3} \right), \quad j = 2, 3. \end{cases}$$

$$\begin{aligned} \mathbf{q}_i &= \frac{1}{M} \left(-\sum_{j=1}^{i-1} m_j \mathbf{q}_{ji} + \sum_{j=i+1}^3 m_j \mathbf{q}_{ij} \right) \\ \mathbf{p}_i &= \frac{m_i}{M} \left(-\sum_{j=1}^{i-1} m_j \mathbf{v}_{ji} + \sum_{j=i+1}^3 m_j \mathbf{v}_{ij} \right) \end{aligned} \quad \text{G3BP in the inertial barycentric frame: } \begin{cases} \frac{d\mathbf{p}_i}{dt} = m_i \left(\sum_{k=1}^{i-1} \frac{m_k (\mathbf{q}_k - \mathbf{q}_i)}{|\mathbf{q}_k - \mathbf{q}_i|^3} - \sum_{k=i+1}^3 \frac{m_k (\mathbf{q}_i - \mathbf{q}_k)}{|\mathbf{q}_i - \mathbf{q}_k|^3} \right), \\ \frac{d\mathbf{q}_i}{dt} = \frac{\mathbf{p}_i}{m_i}, \quad i = 1, 2, 3. \end{cases}$$

Conservation of G3BP ((LogH)₂ vs (TCI)₂)

Conserved quantities of (TCI)₂

Conserved quantities of (LogH)₂ = (TCI)₂ with $\alpha^{(l+1/2)} = 1$

Conserved quantities by Coordinate transformation $(\mathbf{q}_{ij}, \mathbf{v}_{ij}) \rightarrow (\mathbf{q}_i, \mathbf{p}_i)$

* the total linear momentum: $\ell = 0$ * the position of the center of mass: $c = 0$

* the total angular momentum: $\mathbf{a} \equiv \frac{1}{M} \sum_{i=1}^2 \sum_{j=i+1}^3 m_i m_j \mathbf{q}_{ij} \times \mathbf{v}_{ij}$

* the total energy: $E \equiv T_R(\mathbf{v}) + U_R(\mathbf{q}) \leftarrow$ This is accomplished by adjusting $\alpha^{(l+1/2)}$.

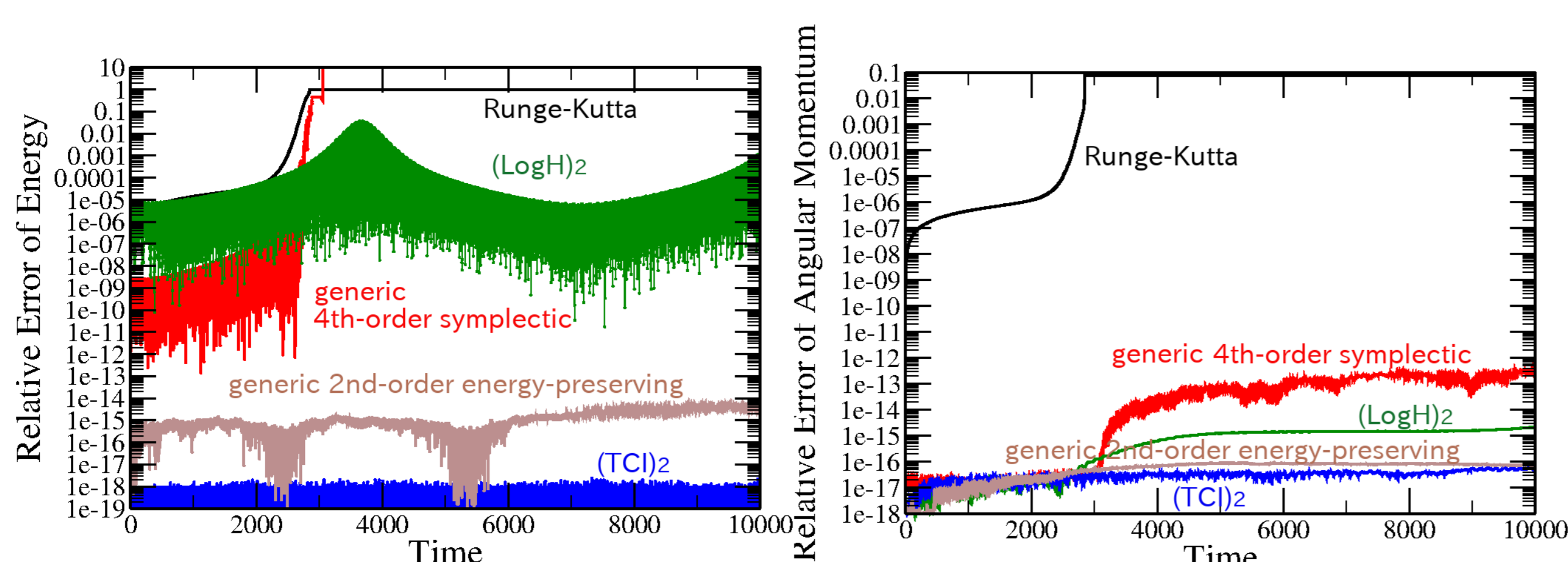


Figure 2: Relative errors of the total energy and total angular momentum for a periodic solution different from Lagrangian solutions.

The above relation for conservation is fulfilled for GNBP.

Triangular Lagrangian Solutions of (TCI)₂

For any integer l , and arbitrary real numbers Θ , and Φ , we assume

$$\begin{aligned} \mathbf{q}_{12}^{(k)} &= \mathbf{q}^{(k)} R_3(\Theta) R_1(\Phi), \quad \mathbf{q}_{13}^{(k)} = \mathbf{q}^{(k)} R_3(\Theta \pm \pi/3) R_1(\Phi), \quad \mathbf{q}_{23}^{(k)} = \mathbf{q}_{13}^{(k)} - \mathbf{q}_{12}^{(k)}, \quad k = l, l+1/2, l+1, \\ \mathbf{v}_{12}^{(k)} &= \mathbf{v}^{(k)} R_3(\Theta) R_1(\Phi), \quad \mathbf{v}_{13}^{(k)} = \mathbf{v}^{(k)} R_3(\Theta \pm \pi/3) R_1(\Phi), \quad \mathbf{v}_{23}^{(k)} = \mathbf{v}_{13}^{(k)} - \mathbf{v}_{12}^{(k)}, \quad k = l, l+1, \end{aligned}$$

(double sign corresponds),

where $R_3(\theta)$, and $R_1(\phi)$ are respectively the rotational matrix about the 3rd, and the 1st axes. Then, (TCI)₂ reduces to the discrete-time general 2-body problem (d-G2BP):

$$\begin{cases} \mathbf{q}^{(l+\frac{1}{2})} = \mathbf{q}^{(l)} + \frac{\Delta \sigma_{LT} \mathbf{v}^{(l)}}{\frac{(\mathbf{v}^{(l)})^2}{2} - \mathcal{E}_{LT}^{(0)}}, \quad t^{(l+1/2)} = t^{(l)} + \frac{\Delta \sigma_{LT}}{\frac{(\mathbf{v}^{(l)})^2}{2} - \mathcal{E}_{LT}^{(0)}}, \\ \mathbf{v}^{(l+1)} = \mathbf{v}^{(l)} - \alpha^{(l+\frac{1}{2})} \frac{\Delta \sigma_{LT} \mathbf{q}^{(l+\frac{1}{2})}}{|\mathbf{q}^{(l+\frac{1}{2})}|^2}, \\ \mathbf{q}^{(l+1)} = \mathbf{q}^{(l+\frac{1}{2})} + \frac{\Delta \sigma_{LT} \mathbf{v}^{(l+1)}}{\frac{(\mathbf{v}^{(l+1)})^2}{2} - \mathcal{E}_{LT}^{(0)}}, \quad t^{(l+1)} = t^{(l+1/2)} + \frac{\Delta \sigma_{LT}}{\frac{(\mathbf{v}^{(l+1)})^2}{2} - \mathcal{E}_{LT}^{(0)}}, \end{cases}$$

where $\Delta \sigma_{LT} \equiv \frac{M \Delta s}{m_1 m_2 + m_1 m_3 + m_2 m_3}$, and $\mathcal{E}_{LT} \equiv \frac{|\mathbf{v}|^2}{2} - \frac{M}{|\mathbf{q}|}$.

$$\text{d-G2BP } \alpha^{(l+1/2)} = 1 \rightarrow (\text{LogH})_2 \text{ for G2BP } \xrightarrow{\Delta s \rightarrow 0} \text{G2BP: } \frac{d\mathbf{q}}{dt} = \mathbf{v}, \quad \frac{d\mathbf{v}}{dt} = -\frac{M\mathbf{q}}{|\mathbf{q}|^3}$$

(LogH)₂ for G2BP [2] maintains all conserved quantities of G2BP, namely, (i) energy: \mathcal{E}_{LT} , (ii) angular velocity: $\mathbf{J}_{LT} \equiv \mathbf{q} \times \mathbf{v}$, and (iii) Laplace vector: $\mathbf{e}_{LT} \equiv \frac{\mathbf{v} \times (\mathbf{q} \times \mathbf{v})}{M} - \frac{\mathbf{q}}{|\mathbf{q}|}$. Therefore, (LogH)₂ for G2BP exactly traces the original G2BP. Further, $\alpha^{(l+1/2)}$ is adjusted to conserve $\mathcal{E}_{LT}^{(0)}$. Accordingly, when (TCI)₂ holds the triangular Lagrangian solutions, (TCI)₂ has $\alpha^{(l+1/2)} = 1$, namely, (TCI)₂ coincides with (LogH)₂ for G2BP. In a similar procedure, we prove that (TCI)₂ has the collinear Lagrangian solutions of G3BP and equilibrium solutions of GNBP.

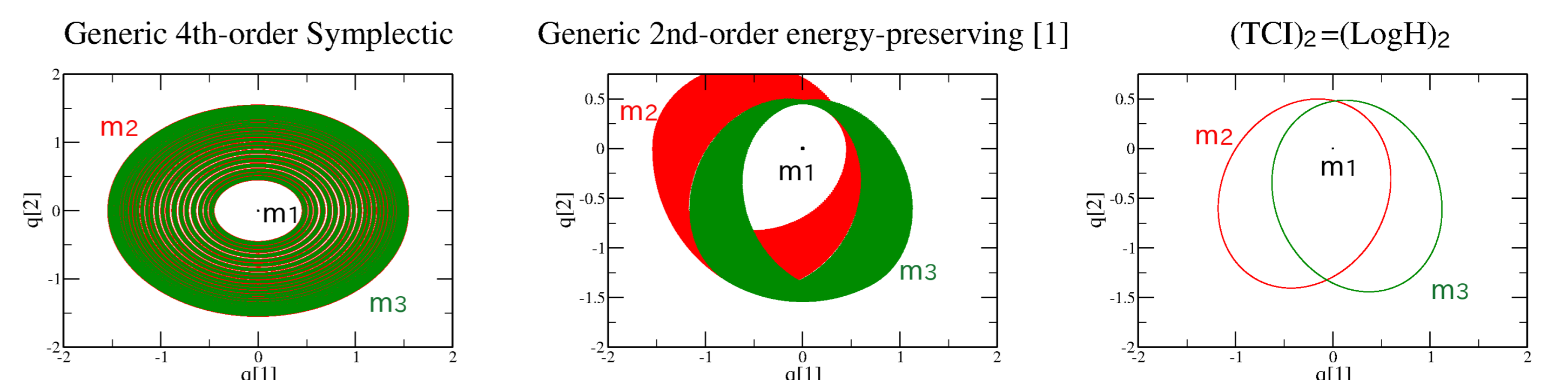


Figure 3: Orbits of a triangular Lagrangian solution in the inertial barycentric frame

Other Periodic Orbits of (TCI)₂

(TCI)₂ is merely 2nd-order accurate, but it can precisely reproduce some periodic orbits which (LogH)₂, and generic geometric integrators cannot do. For example,

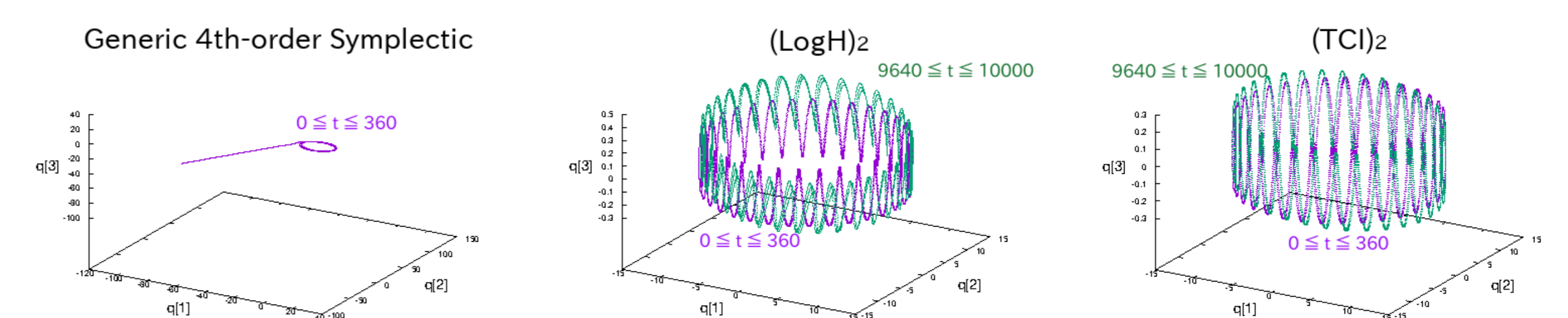


Figure 4: A Periodic Orbit of m_2 in the inertial barycentric frame

Conclusion

We modified (LogH)₂ [2] for GNBP to design a new integration method, (TCI)₂, which maintains all conserved quantities and holds equilibrium solutions including Lagrangian solutions. Although (TCI)₂ is merely 2nd-order accurate, it can precisely trace some periodic orbits which generic geometric integrators, and (LogH)₂ cannot do. Until (TCI)₂, no integration method was known to maintain both preservation of all conserved quantities and the existence of equilibrium solutions.

References

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