

Billiards in confocal quadrics as a pluri-Lagrangian system

Yuri B. Suris

(Technische Universität Berlin)

SIDE 13, Fukuoka, 16.11.2018



Discretization in
Geometry and Dynamics
SFB Transregio 109

Part 1, based on:

Yu. S. *Variational formulation of commuting Hamiltonian flows: multi-time Lagrangian 1-forms*. J. Geometric Mechanics, 2013, **5**, 365–379,

A. Sridhar, Yu. S. *Commutativity in Lagrangian and Hamiltonian mechanics*, J. Geometry and Physics, 2018 (to appear)

Continuous time: principal action

- ▶ non-degenerate Lagrange function $L : TM \rightarrow \mathbb{R}$,
- ▶ corresponding Hamilton function $H : T^*M \rightarrow \mathbb{R}$,
- ▶ *action functional* of a continuous path $q : [t_1, t_2] \rightarrow M$:

$$S[q] = \int_{t_1}^{t_2} L(q(t), \dot{q}(t)) dt,$$

- ▶ *principal action function* $S : M \times M \times \mathbb{R} \rightarrow \mathbb{R}$ – critical value of action functional:

$$S(q_1, q_2, t) = \min \{ S[q] \mid q : [0, t] \rightarrow M, q(0) = q_1, q(t) = q_2 \}.$$

Principal action is a generating function of Hamiltonian flow:

$$\frac{\partial S(q_1, q_2, t)}{\partial q_1} = -p(0), \quad \frac{\partial S(q_1, q_2, t)}{\partial q_2} = p(t),$$

$$\frac{\partial S(q_1, q_2, t)}{\partial t} = -H.$$

(Hamilton-Jacobi equations).

Commuting actions vs. commuting Hamiltonians

Let L_1, L_2 be two non-degenerate Lagrangians, S_1, S_2 their principal action functions.

For $q_0, q_{12} \in M$ and $t_1, t_2 > 0$, let

$$S_{12}(q_0, q_{12}, t_1, t_2) = \min_{q_1 \in M} \left(S_1(q_0, q_1, t_1) + S_2(q_1, q_{12}, t_2) \right),$$

$$S_{21}(q_0, q_{12}, t_2, t_1) = \min_{q_2 \in M} \left(S_2(q_0, q_2, t_2) + S_1(q_2, q_{12}, t_1) \right).$$

Definition. *Principal actions of Lagrangians L_1, L_2 commute, if*

$$S_{12}(q_0, q_{12}, t_1, t_2) = S_{21}(q_0, q_{12}, t_2, t_1).$$

Theorem. *Principal actions of Lagrangians L_1, L_2 commute if and only if corresponding Hamiltonians Poisson commute, $\{H_1, H_2\} = 0$.*

Commuting discrete Lagrangians

Discrete time Lagrangians $\Lambda_i : M \times M \rightarrow \mathbb{R}$ ($i = 1, 2$) – generating functions of symplectic maps

$$F_i : T^*M \ni (q_0, p_0) \mapsto (q_i, p_i) \in T^*M,$$
$$p_0 = -\frac{\partial \Lambda_i(q_0, q_i)}{\partial q_0}, \quad p_i = \frac{\partial \Lambda_i(q_0, q_i)}{\partial q_i}.$$

Definition. *Discrete Lagrangians Λ_1, Λ_2 commute, if the following two functions coincide identically:*

$$S_{12}(q_0, q_{12}) = \min_{q_1 \in M} \left(\Lambda_1(q_0, q_1) + \Lambda_2(q_1, q_{12}) \right)$$

and

$$S_{21}(q_0, q_{12}) = \min_{q_2 \in M} \left(\Lambda_2(q_0, q_2) + \Lambda_1(q_2, q_{12}) \right).$$

Theorem. *If Lagrangians Λ_1, Λ_2 commute, then maps F_1, F_2 commute:*

$$F_1 \circ F_2 = F_2 \circ F_1.$$

Conversely, if maps F_1, F_2 commute, then

$$S_{12}(q_0, q_{12}) - S_{21}(q_0, q_{12}) = \text{const.}$$

Corner equations

Minimizers q_1, q_2 in S_{12}, S_{21} , are solutions of *corner equations*:

$$\frac{\partial \Lambda_1(q_0, q_1)}{\partial q_1} + \frac{\partial \Lambda_2(q_1, q_{12})}{\partial q_1} = 0, \quad (E_1)$$

$$\frac{\partial \Lambda_2(q_0, q_2)}{\partial q_2} + \frac{\partial \Lambda_1(q_2, q_{12})}{\partial q_2} = 0. \quad (E_2)$$

Crucial lemma. *Let Lagrangians Λ_1, Λ_2 commute. If q_1, q_2 satisfy corner equations $(E_1), (E_2)$, then the following two corner equations are satisfied, as well:*

$$\frac{\partial \Lambda_1(q_0, q_1)}{\partial q_0} - \frac{\partial \Lambda_2(q_0, q_2)}{\partial q_0} = 0, \quad (E_0)$$

$$\frac{\partial \Lambda_1(q_2, q_{12})}{\partial q_{12}} - \frac{\partial \Lambda_2(q_1, q_{12})}{\partial q_{12}} = 0. \quad (E_{12})$$

Corner equations

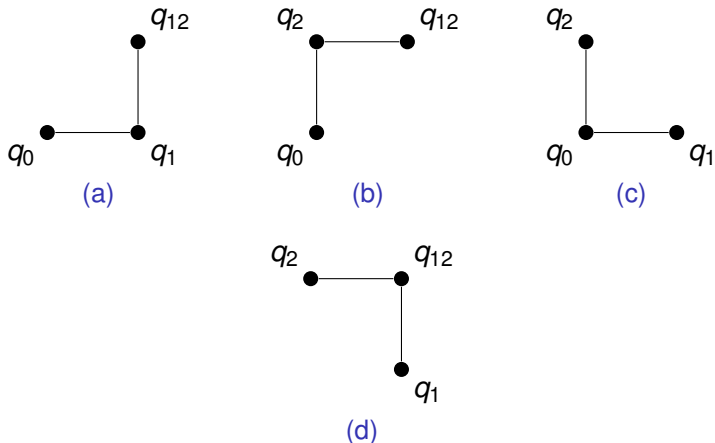


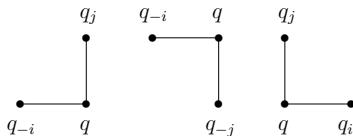
Figure: Four corner equations: (a) (E_1), (b) (E_2), (c) (E_0), (d) (E_{12}).

Pluri-Lagrangian EL equations = corner equations

Function $q : \mathbb{Z}^m \rightarrow M$ solves pluri-Lagrangian problem iff *corner equations* are satisfied everywhere:

$$\begin{aligned}\frac{\partial \Lambda_i(q_{-i}, q)}{\partial q} + \frac{\partial \Lambda_j(q, q_j)}{\partial q} &= 0, \\ \frac{\partial \Lambda_i(q_{-i}, q)}{\partial q} - \frac{\partial \Lambda_j(q_{-j}, q)}{\partial q} &= 0, \\ \frac{\partial \Lambda_i(q, q_i)}{\partial q} - \frac{\partial \Lambda_j(q, q_j)}{\partial q} &= 0\end{aligned}$$

($2m$ equations at each point $n \in \mathbb{Z}^m$, four equations per elementary square σ_{ij}).



Corner equations vs. usual Euler-Lagrange equations

If $q : \mathbb{Z}^m \rightarrow M$ solves a pluri-Lagrangian problem, then symplectic maps $F_i : (q, p) \mapsto (q_i, p_i)$ defined by

$$p = -\frac{\partial \Lambda_i(q, q_i)}{\partial q}, \quad p_i = \frac{\partial \Lambda_i(q, q_i)}{\partial q_i},$$

commute, $F_i \circ F_j = F_j \circ F_i$.

Remark. Standard (single-time) discrete EL equations for F_i ,

$$\frac{\partial \Lambda_i(q_{-i}, q)}{\partial q} + \frac{\partial \Lambda_i(q, q_i)}{\partial q} = 0,$$

are *consequences* of 2D corner equations:

The diagram shows an equation between three configurations of points and lines. On the left, three points are arranged horizontally on a line, labeled from left to right as q_{-i} , q , and q_i . A horizontal line segment with an arrow pointing to the right connects the point q to the point q_i . This is followed by an equals sign. On the right side of the equals sign, there are two configurations separated by a plus sign. The first configuration has three points: q_{-i} , q , and q_j . A horizontal line segment with an arrow pointing to the right connects q to q (representing the point q), and a vertical line segment with an arrow pointing upwards connects q to q_j . The second configuration has three points: q , q , and q_i . A vertical line segment with an arrow pointing downwards connects q to q (representing the point q), and a horizontal line segment with an arrow pointing to the right connects q to q_i .

Almost closedness of multi-time 1-form

The multi-time 1-form is almost closed on solutions of corner equations:

$$d\mathcal{L}(\sigma_{ij}) = \Lambda_i(\mathbf{q}, \mathbf{q}_i) + \Lambda_j(\mathbf{q}_i, \mathbf{q}_{ij}) - \Lambda_i(\mathbf{q}_j, \mathbf{q}_{ij}) - \Lambda_j(\mathbf{q}, \mathbf{q}_j) = \text{const} =: \ell_{ij}.$$

All $\ell_{ij} = 0$ means that \mathcal{L} is closed on solutions, i.e., extremal value of S_Γ does not depend on curve Γ connecting two given points in \mathbb{Z}^m .

Closedness of multi-time 1-form vs. spectrality

Let $F_\lambda : (q, p) \mapsto (\tilde{q}, \tilde{p})$ be a *1-parameter family* of commuting symplectic maps, with Lagrange function $\Lambda(q, \tilde{q}; \lambda)$.

For a second such map, we write $F_\mu : (q, p) \mapsto (\hat{x}, \hat{p})$.

Specifying previous result:

$$\Lambda(q, \tilde{q}; \lambda) + \Lambda(\tilde{q}, \hat{\tilde{q}}; \mu) - \Lambda(q, \hat{\tilde{q}}; \mu) - \Lambda(\hat{\tilde{q}}, \hat{\tilde{q}}; \lambda) = \ell(\lambda, \mu).$$

Theorem. Discrete 1-form \mathcal{L} is closed on solutions of multi-time Euler-Lagrange equations iff

$$\partial\Lambda(q, \tilde{q}; \lambda)/\partial\lambda$$

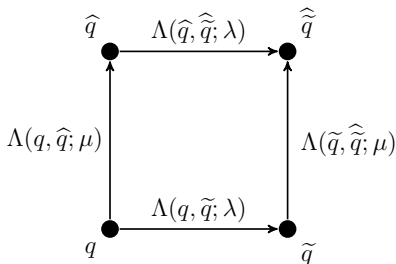
is a common integral of motion for all F_μ (*spectrality*; examples discovered by Kuznetsov-Sklyanin '98).

Closedness of multi-time 1-form vs. spectrality (continued)

Proof. Due to skew-symmetry, $\ell(\lambda, \mu) = 0$ is equivalent to $\partial\ell(\lambda, \mu)/\partial\lambda = 0$, that is, to

$$\frac{\partial\Lambda(q, \tilde{q}; \lambda)}{\partial\lambda} - \frac{\partial\Lambda(\hat{q}, \hat{\tilde{q}}; \lambda)}{\partial\lambda} = 0.$$

This is equivalent to saying that $\partial\Lambda(q, \tilde{q}; \lambda)/\partial\lambda$ is an integral of motion for F_μ . ■



Part 2, based on:

Yu. S. *Billiards in confocal quadrics as a pluri-Lagrangian system*. Theor. and Appl. Mech., 2016, **43**, 221–228.

We consider the billiard in an ellipsoid

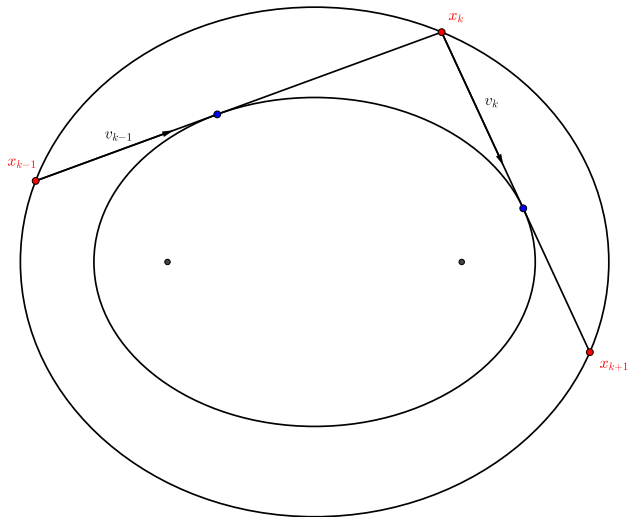
$$Q = \left\{ x \in \mathbb{R}^n : \langle x, A^{-1}x \rangle = \sum_{i=1}^n \frac{x_i^2}{a_i^2} = 1 \right\}.$$

Let $\{x_k\}_{k \in \mathbb{Z}}$, $x_k \in Q$, be an orbit of this billiard. Denote by

$$v_k = \frac{x_{k+1} - x_k}{|x_{k+1} - x_k|} \in S^{n-1}$$

the unit vector along the line $(x_k x_{k+1})$.

Billiard in an ellipse



$$B: \begin{cases} \mathbf{x}_{k+1} - \mathbf{x}_k = \mu_k \mathbf{v}_k, \\ \mathbf{v}_k - \mathbf{v}_{k-1} = \nu_k \mathbf{A}^{-1} \mathbf{x}_k. \end{cases}$$

Here μ_k, ν_k are found from $|\mathbf{v}_k| = 1$ and $\langle \mathbf{x}_k, \mathbf{A}^{-1} \mathbf{x}_k \rangle = 1$:

$$\mu_k = |\mathbf{x}_{k+1} - \mathbf{x}_k|,$$

$$\nu_k = \langle \mathbf{v}_k - \mathbf{v}_{k-1}, \mathbf{A}(\mathbf{v}_k - \mathbf{v}_{k-1}) \rangle^{1/2}.$$

First (traditional) Lagrangian formulation

Eliminate ν_k :

$$\frac{x_{k+1} - x_k}{\mu_k} - \frac{x_k - x_{k-1}}{\mu_{k-1}} = \nu_k \mathbf{A}^{-1} x_k,$$

or

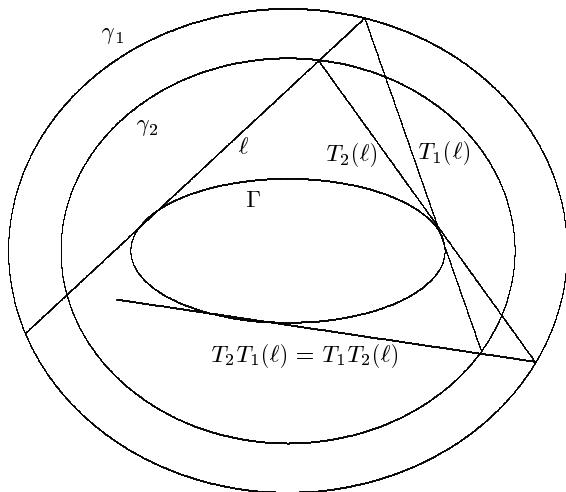
$$\frac{x_{k+1} - x_k}{|x_{k+1} - x_k|} - \frac{x_k - x_{k-1}}{|x_k - x_{k-1}|} = \nu_k \mathbf{A}^{-1} x_k.$$

This is EL equation for the discrete Lagrange function

$$L : \mathcal{Q} \times \mathcal{Q} \rightarrow \mathbb{R}, \quad L(x_k, x_{k+1}) = |x_{k+1} - x_k|,$$

with Lagrange multiplier ν_k ensuring $x_k \in \mathcal{Q}$.

Commuting elliptic billiards



Billiard as a map on the space of lines

To formulate this correctly, B should be interpreted as a map on \mathcal{L} , the space of oriented lines in \mathbb{R}^n :

$$(x, v) \in \mathbb{R}^n \times S^{n-1} \quad \leftrightarrow \quad \ell = \{x + tv : t \in \mathbb{R}\} \in \mathcal{L}.$$

Replace here $x \in \ell$ by $x' = x - \langle x, v \rangle v \in \ell$, so that $\langle x', v \rangle = 0$,

$$x' \in T_v S^{n-1} \simeq T_v^* S^{n-1}.$$

Thus, one can identify

$$\mathcal{L} \simeq T^* S^{n-1},$$

and the billiard map can be considered as

$$B : T^* S^{n-1} \rightarrow T^* S^{n-1}.$$

Theorem. For any two quadrics Q_λ and Q_μ from the confocal family

$$Q_\lambda = \{x \in \mathbb{R}^n : Q_\lambda(x) = 1\},$$

where

$$Q_\lambda(x) := \langle x, (A + \lambda I)^{-1} x \rangle = \sum_{i=1}^n \frac{x_i^2}{a_i^2 + \lambda},$$

the corresponding maps $B_\lambda : T^*S^{n-1} \rightarrow T^*S^{n-1}$ and $B_\mu : T^*S^{n-1} \rightarrow T^*S^{n-1}$ commute.

Second (“dual”) Lagrangian formulation

To find a Lagrange function $L : S^{n-1} \times S^{n-1} \rightarrow \mathbb{R}$ for the map $B : T^*S^{n-1} \rightarrow T^*S^{n-1}$, eliminate variables x_k :

$$\frac{A(v_{k+1} - v_k)}{\nu_{k+1}} - \frac{A(v_k - v_{k-1})}{\nu_k} = \mu_k v_k,$$

or

$$\frac{A(v_{k+1} - v_k)}{\langle v_{k+1} - v_k, A(v_{k+1} - v_k) \rangle^{1/2}} - \frac{A(v_k - v_{k-1})}{\langle v_k - v_{k-1}, A(v_k - v_{k-1}) \rangle^{1/2}} = \mu_k v_k.$$

This is EL equation for the discrete Lagrange function

$$L : S^{n-1} \times S^{n-1} \rightarrow \mathbb{R}, \quad L(v_k, v_{k+1}) = \langle v_{k+1} - v_k, A(v_{k+1} - v_k) \rangle^{1/2},$$

with Lagrange multiplier μ_k ensuring $v_k \in S^{n-1}$.

Consequence: B preserves the canonical 2-form on T^*S^{n-1} .

A novel derivation of a result originally due to J. Moser.

Theorem. The maps $B_\mu : T^*S^{n-1} \rightarrow T^*S^{n-1}$ have a set of common integrals of motion

$$F_i(v, x) = v_i^2 + \sum_{j \neq i} \frac{(x_i v_j - x_j v_i)^2}{a_i^2 - a_j^2}, \quad 1 \leq i \leq n.$$

Only $n - 1$ of them are functionally independent, due to $\sum_{i=1}^n F_i = \langle v, v \rangle = 1$.

Proof. The value of the constant

$$dL(\lambda, \mu) := L(v, \tilde{v}; \lambda) + L(\tilde{v}, \hat{v}; \mu) - L(\hat{v}, \hat{v}; \lambda) - L(v, \hat{v}; \mu)$$

is easily determined on a concrete billiard trajectory along the big axis of Q_λ, Q_μ , for which $v = (1, 0, \dots, 0)$, $\tilde{v} = \hat{v} = -v$, and $\hat{\tilde{v}} = v$. Recall that

$$L(v, \tilde{v}; \lambda) = \langle \tilde{v} - v, (A + \lambda I)(\tilde{v} - v) \rangle^{1/2}.$$

There follows immediately that $dL(\lambda, \mu) = 0$. Now find a generating function of common integral of motion for all B_μ :

$$\begin{aligned} \frac{\partial L(\underline{v}, v; \lambda)}{\partial \lambda} &= \frac{\langle v - \underline{v}, v - \underline{v} \rangle}{\langle v - \underline{v}, (A + \lambda I)(v - \underline{v}) \rangle^{1/2}} \\ &= 2 \langle x, (A + \lambda I)^{-1} v \rangle. \end{aligned}$$

Thus,

$$Q_\lambda(x, v) := \langle x, (A + \lambda I)^{-1} v \rangle = \sum_{i=1}^n \frac{x_i v_i}{\lambda + a_i^2}$$

with $v \in S^{n-1}$, $x \in Q_\lambda$, is an integral of motion for all maps $B_\mu : \mathcal{L} \rightarrow \mathcal{L}$.

To find $F_i(x, v)$ manifestly independent on the choice of $x \in \ell \cap Q_\lambda$, observe: as soon as $Q_\lambda(x) = 1$, we have

$$\begin{aligned} Q_\lambda^2(x, v) &= Q_\lambda(v) - Q_\lambda(v)Q_\lambda(x) + Q_\lambda^2(x, v) \\ &= \sum_{i=1}^n \frac{F_i(v, x)}{\lambda + a_i^2}. \quad \blacksquare \end{aligned}$$

The notion of pluri-Lagrangian systems can serve as integrability of discrete and continuous variational systems.

- ▶ (Almost) closedness of the Lagrangian form ($d\mathcal{L} = \text{const}$) on solutions of the pluri-Lagrangian system built-in.
- ▶ Closedness of the Lagrangian form ($d\mathcal{L} = 0$) on solutions is related to existence of integrals of motion (resp. conservation laws) in the discrete case, and to involutivity of Hamiltonians in the continuous case.
- ▶ Classification of pluri-Lagrangian systems looks promising.